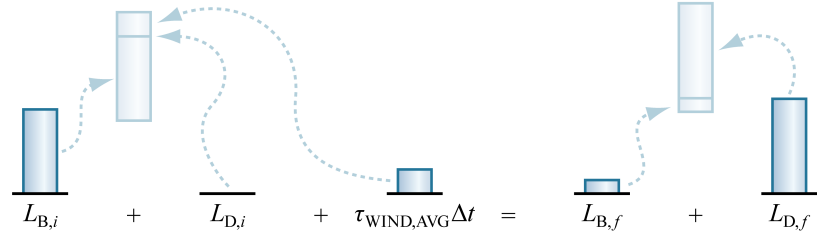
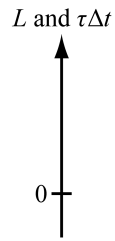
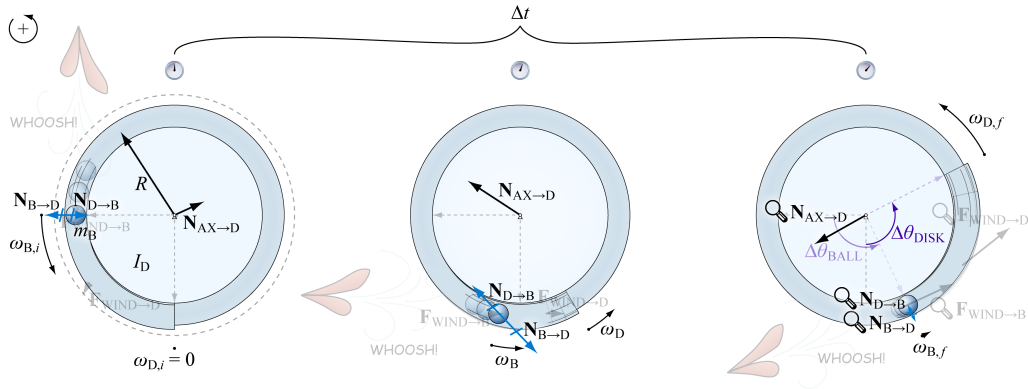
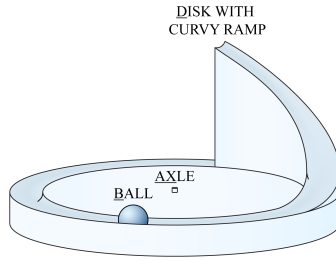
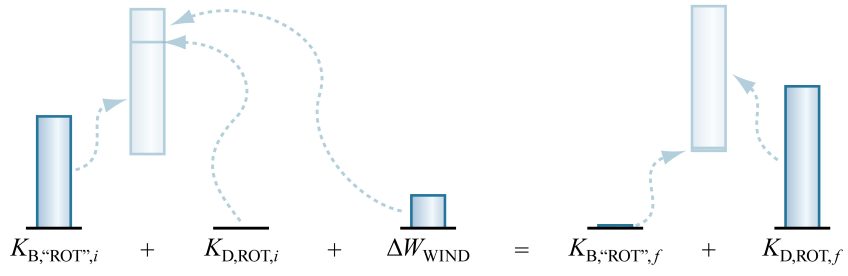
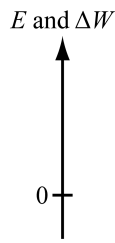


Sums of rotational quantities can be changed by input



$$\Sigma L_i + \left(\sum_{EXT \rightarrow SYS} \tau_{AVG} \right) \Delta t = \Sigma L_f$$



$$\underbrace{\Sigma ME_{SYS,i}}_{\Sigma K_i + \Sigma U_{G,i} + \Sigma U_{S,i}} + \Sigma \Delta W_{OUF} = \underbrace{\Sigma ME_{SYS,f}}_{\Sigma K_f + \Sigma U_{G,f} + \Sigma U_{S,f}} + \Sigma \Delta U_{INT}$$